Two-dimensional spatial patterning in developmental systems

Keiko U. Torii





Is pigment patterning in fish skin determined by the Turing mechanism?

Masakatsu Watanabe and Shigeru Kondo

Graduate School of Frontier Biosciences, Osaka University, Osaka, 565-0871, Japan



Hox Genes Regulate Digit Patterning by Controlling the Wavelength of a Turing-Type Mechanism

Rushikesh Sheth,¹*† Luciano Marcon,^{2,3}* M. Félix Bastida,^{1,4} Marisa Junco,¹ Laura Quintana,^{2,3} Randall Dahn,⁵ Marie Kmita,⁶‡ James Sharpe,^{2,3,7}‡ Maria A. Ros^{1,4}‡





Using Engineered Scaffold Interactions to Reshape MAP Kinase Pathway Signaling Dynamics

Caleb J. Bashor,^{1,2} Noah C. Helman,¹ Shude Yan,¹ Wendell A. Lim¹*



Secreting and Sensing the Same Molecule Allows Cells to Achieve Versatile Social Behaviors

Hyun Youk^{1,2} and Wendell A. Lim^{1,2,3}*

A Addition of positive feedback link







A synthetic approach reveals extensive tunability of auxin signaling

Kyle A. Havens¹, Jessica M. Guseman¹, Seunghee S. Jang¹, Edith Pierre-Jerome¹, Nick Bolten, Eric Klavins^{*}, Jennifer L. Nemhauser^{*}





Synthetic Cell to Cell Communication



A. Khakhar, N. Bolten, J. Nemhauser, and E. Klavins. 2015

Auxin Meets CRISPR ╺╘<u>╼</u>┚ ╶╤╶╴╤╴

RECV



SEND



A. tumefaciens attached to a carrot cell (Wikipedia)



Time (minutes)

Cooperativity To Increase Turing Pattern Space for Synthetic Biology

Luis Diambra,*^{,†,§} Vivek Raj Senthivel,^{‡,§} Diego Barcena Menendez,^{‡,§} and Mark Isalan^{*,‡,§}

- What do we need to get activator inhibitor patterning ?
- Faster diffusion of the inhibitor than the activator
- High cooperativity/non-linearity
- Faster degradation of the activator
- ...

Using Engineered Scaffold Interactions to Reshape MAP Kinase Pathway Signaling Dynamics

Caleb J. Bashor,^{1,2} Noah C. Helman,¹ Shude Yan,¹ Wendell A. Lim^{1*}



Using Engineered Scaffold Interactions to Reshape MAP Kinase Pathway Signaling Dynamics

Caleb J. Bashor,^{1,2} Noah C. Helman,¹ Shude Yan,¹ Wendell A. Lim^{1*}



Secreting and Sensing the Same Molecule Allows Cells to Achieve Versatile Social Behaviors

Hyun Youk^{1,2} and Wendell A. Lim^{1,2,3}*

A Addition of positive feedback link & signal degradation (Bar1)



molecule	measured context	diffusion coefficient (µm²/s)	BNID
H ₂ O	water	2000	104087, 106703
H ₂ O	nucleus of chicken erythrocyte	200	104645
H^+ (from H_3O^+ to H_2O)	water	7000	106702
0 ₂	water	2000	104440
CO ₂	water	2000	102625
tRNA (≈20 kDa)	water	100	107933, 107935
protein (≈30 kDa GFP)	water	100	100301
protein (≈30 kDa GFP)	eukaryotic cell (CHO) cytoplasm	30	101997
protein (≈30 kDa GFP)	rat liver mitochondria	30	100300
protein (NLS-EGFP)	cytoplasm of <i>D. melanogaster</i> embryo	20	109209
protein (≈30 kDa)	E. coli cytoplasm	7-8	100193, 107985
protein (≈40 kDa)	<i>E. coli</i> cytoplasm	2-4	107985
protein (≈70-250 kDa)	<i>E. coli</i> cytoplasm	0.4-2	107985
protein (≈140 kDa Tar-YFP)	<i>E. coli</i> membrane	0.2	107985
protein (≈70 kDa LacY-YFP)	E. coli membrane	0.03	107985
fluorescent dye (carboxy-fluorescein)	A. thaliana cell wall	30	105033
fluorescent dye (carboxy-fluorescein)	A. thaliana mature root epidermis	3	105034
transcription factor (Lacl)	movement along DNA (1D, in vitro)	0.04 (4×10 ⁵ bp ² s ⁻¹)	102036
morphogen (bicoid-GFP)	cytoplasm of D. melanogaster embryo	7	109199
morphogen (wingless)	wing imaginal disk of D. melanogaster	0.05	101072
mRNA	HeLa nucleus	0.03-0.10	107613
mRNA	various localizations and sizes	0.005-1	110667
ribosome	E. coli	0.04	108596

A chemical approach to designing Turing patterns in reaction-diffusion systems

(pattern formation/nonlinear dynamics)

ISTVÁN LENGYEL*[†] AND IRVING R. EPSTEIN*[‡]

$$X + S \rightleftharpoons SX, \quad K = \frac{sx}{s \cdot x} = \frac{k_+}{k_-}, \quad K' = Ks_0.$$
 [2]

If the spatial distribution of S is uniform, the new reactiondiffusion system is described by

$$\frac{\partial x}{\partial t} = f(x, y, p) - k_+ s_0 x + k_- s x + D_x \frac{\partial^2 x}{\partial z^2}$$
 [3a]

$$\frac{\partial y}{\partial t} = g(x, y, p) + D_y \frac{\partial^2 y}{\partial z^2}$$
 [3b]

$$\frac{\partial sx}{\partial t} = k_+ s_0 x - k_- sx.$$
 [3c]